

## NUC230/NUC240 CMSIS BSP Directory

Directory Introduction for 32-bit NuMicro™ Family

### Directory Information

<b>Document</b>	Driver reference manual and revision history.
<b>Library</b>	Driver header and source files.
<b>SampleCode</b>	Driver sample code.

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## 1 Document Information

BSP Revision History	Show all the revision history about specific BSP.
Driver Reference Guide	Describe the definition, input and output of each API.

## 2 Library Information

CMSIS	CMSIS definitions by ARM® Corp.
Device	CMSIS compliant device header file.
StdDriver	All peripheral driver header and source files.

### 3 Sample Code Information

<b>\SampleCode\CardReader</b>	CCID <sup>[1]</sup> Smart Card reader Sample Code.
<b>\SampleCode\Hard_Fault_Sample</b>	Show hard fault information when hard fault happened.
<b>\SampleCode \ISP</b>	Sample codes for In-System-Programming.
<b>\SampleCode\Template</b>	Software Development Template.
<b>\SampleCode\Semihost</b>	A sample code to show how to debug with semihost message print.
<b>\SampleCode\RegBased</b>	The sample codes which access control registers directly.
<b>\SampleCode\StdDriver</b>	NUC230/NUC240 Series Driver Samples

1. Circuit card interface device (CCID) is USB device that interface with integrated circuit cards.

#### 4 \SampleCode\ISP

<b>ISP_CAN</b>	In-System-Programming Sample code through CAN interface.
<b>ISP_DFU</b>	In-System-Programming Sample code through USB interface and following Device Firmware Upgrade Class Specification.
<b>ISP_HID</b>	In-System-Programming Sample code through USB HID interface.
<b>ISP_I2C</b>	In-System-Programming Sample code through I2C interface.
<b>ISP_RS485</b>	In-System-Programming Sample code through RS485 interface.
<b>ISP_SPI</b>	In-System-Programming Sample code through SPI interface.
<b>ISP_UART</b>	In-System-Programming Sample code through UART interface.

## 5 \SampleCode\RegBased

<b>ACMP</b>	Demonstrate how ACMP <sup>[1]</sup> works with internal band-gap voltage.
<b>ACMP_Wakeup</b>	Show how to wake up MCU from Power-down mode by ACMP wake-up function.
<b>ADC_ContinuousScanMode</b>	Demonstrate how to use continuous scan mode and finishes two cycles of conversion for the specified channels.
<b>ADC_MeasureAVDD</b>	Measure AVDD voltage by ADC.
<b>ADC_PwmTrigger</b>	Demonstrate how to trigger ADC by PWM.
<b>ADC_ResultMonitor</b>	Demonstrate how to use the digital compare function to monitor the conversion result of channel 2.
<b>ADC_SingleCycleScanMode</b>	Demonstrate how to use single cycle scan mode and finishes one cycle of conversion for the specified channels.
<b>ADC_SingleMode</b>	Demonstrate how to use single mode and finishes the conversion of the specified channel.
<b>CAN_Set_MaskFilter</b>	Demonstrate how to use MaskFilter to receive message in Normal mode. The sample code needs to work with CAN_Test_MaskFilter.
<b>CAN_Test_MaskFilter</b>	Demonstrate how to use message object No.1 to send message objects (ID=0x700~0x70F). The sample code needs to work with CAN_Set_MaskFilter.
<b>CRC_8</b>	Perform CRC-8 operation and get the CRC checksum result.
<b>CRC_CCITT</b>	Perform CRC_CCITT operation and get the CRC checksum result.
<b>EBI_NOR</b>	Configure EBI interface to access W39L040P (NOR Flash) on EBI interface.
<b>EBI_SRAM</b>	Configure EBI interface to access BS616LV4017 (SRAM) with PDMA transfer on EBI interface.

<b>FMC_IAP</b>	Show how to call LDROM functions from APROM. The code in APROM will look up the table at 0x100E00 to get the address of function of LDROM and call the function.
<b>FMC_MultiBoot</b>	Implement a multi-boot system to boot from different applications in APROM. A LDROM code and four APROM code are implemented in this sample code.
<b>FMC_RW</b>	Demonstrate how to read/program embedded flash by ISP function.
<b>GPIO_EINTAndDebounce</b>	Demonstrate how to use GPIO external interrupt function and de-bounce function.
<b>GPIO_INT</b>	Demonstrate how to use GPIO interrupt function.
<b>GPIO_OutputInput</b>	Demonstrate how to set GPIO pin mode and use pin data input/output control.
<b>GPIO_PowerDown</b>	Demonstrate how to wake-up form Power-down mode by GPIO interrupt.
<b>I2C_EEPROM</b>	Demonstrate how to access EEPROM by I <sup>2</sup> C interface.
<b>I2C_GCMode_MASTER</b>	Demonstrate how a Master uses I <sup>2</sup> C address 0x0 to write data to I <sup>2</sup> C Slave. Needs to work with I2C_GCMode_SLAVE sample code.
<b>I2C_GCMode_SLAVE</b>	Demonstrate how to receive Master data in GC (General Call) mode. Needs to work with I2C_GCMode_MASTER sample code.
<b>I2C_MASTER</b>	Demonstrate how a Master access Slave. Needs to work with I2C_SLAVE sample code.
<b>I2C_SLAVE</b>	Demonstrate how to set I <sup>2</sup> C in slave mode to receive the data of a Master. Needs to work with I2C_MASTER sample code.
<b>I2C_Wakeup_Master</b>	Demonstrate how to wake-up MCU from power-down. Needs to work with I2C_Wakeup_Slave sample code.
<b>I2C_Wakeup_Slave</b>	Demonstrate how to set I <sup>2</sup> C to wake-up MCU from power-down mode. Needs to work with I2C_Wakeup_Master

	sample code.
<b>I2S_Master</b>	Demonstrate how I <sup>2</sup> S works in Master mode. This sample code needs to work with I2S_Slave sample code.
<b>I2S_PDMA</b>	Demonstrate how I2S works with PDMA in Master mode. Both TX PDMA function and RX PDMA function will be enabled.
<b>I2S_Slave</b>	Demonstrate how I <sup>2</sup> S works in Slave mode. This sample code needs to work with I2S_Master sample code.
<b>PDMA</b>	Demonstrate how to use PDMA channel 6 to transfer data from memory to memory.
<b>PS2</b>	Demonstrate how to control PS/2 mouse movement on the screen.
<b>PWM_Capture</b>	Demonstrate how to use PWMB Channel 2 captures PWMB Channel 1 Waveform.
<b>PWM_DeadZone</b>	Demonstrate how to use PWM Dead Zone function.
<b>PWM_DoubleBuffer</b>	Use PWM Double Buffer function to change duty cycle and period of output waveform.
<b>RTC_PowerDown</b>	Demonstrate how to use RTC alarm interrupt event to wake-up system.
<b>RTC_TimeAndTick</b>	Demonstrate how to get the current RTC data/time per tick.
<b>SCUART_TxRx</b>	Demonstrate how to use smartcard interface UART mode to print "Hello World!"
<b>SPI_Loopback</b>	Implement SPI Master loop back transfer. This sample code needs to connect SPI0_MISO0 pin and SPI0_MOSI0 pin together. It will compare the received data with transmitted data.
<b>SPI_MasterFifoMode</b>	Demonstrate how to communicate with an off-chip SPI slave device with FIFO mode. This sample code needs to work with SPI_SlaveFifoMode sample code.
<b>SPI_PDMA_Loopback</b>	Demonstrate SPI data transfer with PDMA. SPI0 will be configured as Master mode and SPI1 will be configured as



	Slave mode. Both TX PDMA function and RX PDMA function will be enabled.
<b>SPI_SlaveFifoMode</b>	Demonstrate how to communicate with an off-chip SPI master device with FIFO mode. This sample code needs to work with SPI_MasterFifoMode sample code.
<b>SYS</b>	Demonstrate how to change system clock to different PLL frequency and output system clock from CLKO pin.
<b>TIMER_Capture</b>	Demonstrate how to use timer2 capture event to capture timer2 counter value.
<b>TIMER_Counter</b>	Demonstrate how to use timer1 counter input function to count the input event.
<b>TIMER_PeriodicINT</b>	Demonstrate how to perform timer counting in periodic mode.
<b>TIMER_PowerDown</b>	Demonstrate how to use timer0 toggle-output interrupt event to wake-up system.
<b>UART_Autoflow_Master</b>	Demonstrate how to transmit and receive data with auto flow control. The sample code needs to work with UART_Autoflow_Slave.
<b>UART_Autoflow_Slave</b>	Demonstrate how to transmit and receive data with auto flow control. The sample code needs to work with UART_Autoflow_Master.
<b>UART_IrDA_Master</b>	Demonstrate how to transmit and receive data in UART IrDA mode. The sample code needs to work with UART_IrDA_Slave.
<b>UART_IrDA_Slave</b>	Demonstrate how to transmit and receive data in UART IrDA mode. The sample code needs to work with UART_IrDA_Master.
<b>UART_LIN</b>	Demonstrate how to transmit LIN header and response.
<b>UART_PDMA</b>	Transmit and receive UART data with PDMA.
<b>UART_RS485_Master</b>	Demonstrate how to transmit and receive data in UART RS485 mode. The sample code needs to work with UART_RS485_Slave.

<b>UART_RS485_Slave</b>	Demonstrate how to transmit and receive data in UART RS485 mode. The sample code needs to work with UART_RS485_Master.
<b>UART_TxRx_Function</b>	Demonstrate how UART transmit and receive data from PC terminal through RS232 interface.
<b>UART_Wakeup</b>	Show how to wake up system form Power-down mode by UART interrupt.
<b>WDT_PowerDown</b>	Demonstrate how to use WDT time-out interrupt event to wake-up system.
<b>WDT_TimeoutINT</b>	Select one WDT time-out interval period time to generate time-out interrupt event.
<b>WDT_TimeoutReset</b>	Demonstrate how to cause WDT time-out reset system event while WDT time-out reset delay period expired.
<b>WWDT_CompareINT</b>	Select one WWDT window compare value to generate window compare match interrupt event.

1. Analog Comparator (ACMP).

## 6 \SampleCode\StdDriver

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<b>ACMP_Wakeup</b>	Show how to wake up MCU from Power-down mode by ACMP wake-up function.
<b>ADC_ContinuousScanMode</b>	Demonstrate how to use continuous scan mode and finishes two cycles of conversion for the specified channels.
<b>ADC_MeasureAVDD</b>	Measure AVDD voltage by ADC.
<b>ADC_PwmTrigger</b>	Demonstrate how to trigger ADC by PWM.
<b>ADC_ResultMonitor</b>	Demonstrate how to use the digital compare function to monitor the conversion result of channel 2.
<b>ADC_SingleCycleScanMode</b>	Demonstrate how to use single cycle scan mode and finishes one cycle of conversion for the specified channels.
<b>ADC_SingleMode</b>	Demonstrate how to use single mode and finishes the conversion of the specified channel.
<b>CAN_BasicMode_Receive</b>	Demonstrate how to receive message in Basic mode. The sample code needs to work with CAN_BasicMode_Transmit.
<b>CAN_BasicMode_Transmit</b>	Demonstrate how to transmit message in Basic mode. The sample code needs to work with CAN_BasicMode_Receive.
<b>CAN_NormalMode_Receive</b>	Demonstrate how to receive message in Normal mode. The sample code needs to work with CAN_NormalMode_Transmit.
<b>CAN_NormalMode_Transmit</b>	Demonstrate how to transmit message in Normal mode. The sample code needs to work with CAN_NormalMode_Receive.
<b>CRC_8</b>	Perform CRC-8 operation and get the CRC checksum result.

<b>CRC_CCITT</b>	Perform CRC_CCITT operation and get the CRC checksum result.
<b>EBI_NOR</b>	Configure EBI interface to access W39L040P (NOR Flash) on EBI interface.
<b>EBI_SRAM</b>	Configure EBI interface to access BS616LV4017 (SRAM) with PDMA transfer on EBI interface.
<b>FMC_IAP</b>	Show how to call LDROM functions from APROM. The code in APROM will look up the table at 0x100E00 to get the address of function of LDROM and call the function.
<b>FMC_MultiBoot</b>	Implement a multi-boot system to boot from different applications in APROM. A LDROM code and four APROM code are implemented in this sample code.
<b>GPIO_EINTAndDebounce</b>	Demonstrate how to use GPIO external interrupt function and de-bounce function.
<b>GPIO_INT</b>	Demonstrate how to use GPIO interrupt function.
<b>GPIO_OutputInput</b>	Demonstrate how to set GPIO pin mode and use pin data input/output control.
<b>GPIO_PowerDown</b>	Demonstrate how to wake-up form Power-down mode by GPIO interrupt.
<b>I2C_EEPROM</b>	Demonstrate how to access EEPROM by I <sup>2</sup> C interface.
<b>I2C_GCMode_MASTER</b>	Demonstrate how a Master uses I <sup>2</sup> C address 0x0 to write data to I <sup>2</sup> C Slave. Needs to work with I2C_GCMode_SLAVE sample code.
<b>I2C_GCMode_SLAVE</b>	Demonstrate how to receive Master data in GC (General Call) mode. Needs to work with I2C_GCMode_MASTER sample code.
<b>I2C_MASTER</b>	Demonstrate how a Master access Slave. Needs to work with I2C_SLAVE sample code.
<b>I2C_SLAVE</b>	Demonstrate how to set I <sup>2</sup> C in slave mode to receive the data of a Master. Needs to work with

	I2C_MASTER sample code.
<b>I2C_Wakeup_Master</b>	Demonstrate how to wake-up MCU from power-down. Needs to work with I2C_Wakeup_Slave sample code.
<b>I2C_Wakeup_Slave</b>	Demonstrate how to set I <sup>2</sup> C to wake-up MCU from power-down mode. Needs to work with I2C_Wakeup_Master sample code.
<b>I2S_Master</b>	Demonstrate how I <sup>2</sup> S works in Master mode. This sample code needs to work with I2S_Slave sample code.
<b>I2S_PDMA</b>	Demonstrate how I2S works with PDMA in Master mode. Both TX PDMA function and RX PDMA function will be enabled.
<b>I2S_Slave</b>	Demonstrate how I <sup>2</sup> S works in Slave mode. This sample code needs to work with I2S_Master sample code.
<b>PDMA</b>	Demonstrate how to use PDMA channel 6 to transfer data from memory to memory.
<b>PS2</b>	Demonstrate how to control PS/2 mouse movement on the screen.
<b>PWM_Capture</b>	Demonstrate how to use PWMB Channel 2 captures PWMB Channel 1 Waveform.
<b>PWM_DeadZone</b>	Demonstrate how to use PWM Dead Zone function.
<b>PWM_DoubleBuffer</b>	Use PWM Double Buffer function to change duty cycle and period of output waveform.
<b>RTC_PowerDown</b>	Demonstrate how to use RTC alarm interrupt event to wake-up system.
<b>RTC_TimeAndTick</b>	Demonstrate how to get the current RTC data/time per tick.
<b>SC_ReadATR</b>	Demonstrate how to get smart card ATR data.
<b>SCUART_TxRx</b>	Demonstrate how to use smartcard interface UART mode to print "Hello World!"

<b>SPI_Loopback</b>	Implement SPI Master loop back transfer. This sample code needs to connect SPI0_MISO0 pin and SPI0_MOSI0 pin together. It will compare the received data with transmitted data.
<b>SPI_MasterFifoMode</b>	Configure SPI0 as Master mode and demonstrate how to communicate with an off-chip SPI Slave device with FIFO mode. This sample code needs to work with SPI_SlaveFifoMode sample code.
<b>SPI_PDMA_Loopback</b>	Demonstrate SPI data transfer with PDMA. SPI0 will be configured as Master mode and SPI1 will be configured as Slave mode. Both TX PDMA function and RX PDMA function will be enabled.
<b>SPI_SlaveFifoMode</b>	Configure SPI0 as Slave mode and demonstrate how to communicate with an off-chip SPI Master device with FIFO mode. This sample code needs to work with SPI_MasterFifoMode sample code.
<b>SYS</b>	Demonstrate how to change system clock to different PLL frequency and output system clock from CLKO pin.
<b>TIMER_Capture</b>	Demonstrate how to use timer2 capture event to capture timer2 counter value.
<b>TIMER_Counter</b>	Demonstrate how to use timer1 counter input function to count the input event.
<b>TIMER_PeriodicINT</b>	Demonstrate how to perform timer counting in periodic mode.
<b>TIMER_PowerDown</b>	Demonstrate how to use timer0 toggle-output interrupt event to wake-up system.
<b>UART_Autoflow_Master</b>	Demonstrate how to transmit and receive data with auto flow control. The sample code needs to work with UART_Autoflow_Slave.
<b>UART_Autoflow_Slave</b>	Demonstrate how to transmit and receive data with auto flow control. The sample code needs to work with UART_Autoflow_Master.

<b>UART_IrDA_Master</b>	Demonstrate how to transmit and receive data in UART IrDA mode. The sample code needs to work with UART_IrDA_Slave.
<b>UART_IrDA_Slave</b>	Demonstrate how to transmit and receive data in UART IrDA mode. The sample code needs to work with UART_IrDA_Master.
<b>UART_LIN</b>	Demonstrate how to transmit LIN header and response.
<b>UART_PDMA</b>	Transmit and receive UART data with PDMA.
<b>UART_RS485_Master</b>	Demonstrate how to transmit and receive data in UART RS485 mode. The sample code needs to work with UART_RS485_Slave.
<b>UART_RS485_Slave</b>	Demonstrate how to transmit and receive data in UART RS485 mode. The sample code needs to work with UART_RS485_Master.
<b>UART_TxRx_Function</b>	Demonstrate how UART transmit and receive data from PC terminal through RS232 interface.
<b>UART_Wakeup</b>	Show how to wake up system form Power-down mode by UART interrupt.
<b>USBD_HID_Keyboard</b>	Demonstrate how to implement a USB keyboard device. It supports to use GPIO to simulate key input.
<b>USBD_HID_Mouse</b>	Demonstrate how to implement a USB mouse device. The mouse cursor will move automatically when this mouse device connecting to PC by USB.
<b>USBD_MassStorage_DataFlash</b>	Demonstrate how to implement a USB Mass-Storage. It uses embedded data flash as storage.
<b>USBD_VCOM</b>	Demonstrate how to implement a USB virtual COM port device. It supports one virtual COM port.
<b>USBD_Audio_NAU8822</b>	Demonstrate how to implement a USB audio class device. NAU8822 is used in this sample code to play the audio data from Host. It also supports to record data from NAU8822 to Host.

**USBD\_HID\_Transfer**

Demonstrate how to transfer data between USB device and PC through USB HID interface. A windows tool is also included in this sample code to connect with USB device.



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